## COMP5212: Machine Learning <br> Lecture 9

## From last time

## Shattered

- Given a set $S=\left\{x^{(i)}, \ldots, x^{(d)}\right\}$ (no relation to the training set) of points $x^{(i)} \in \mathscr{X}$, we say that $\mathscr{H}$ shatters $S$ if $\mathscr{H}$ can realize any labeling on $S$. I.e, if for any set of labels $\left\{y^{(i)}, \ldots, y^{(d)}\right\}$, there exist some $h \in \mathscr{H}$ so that $h\left(x^{(i)}\right)=y^{(i)}$ for all $i=1, \ldots, d$


## Break point of $\mathscr{H}$

- If no data set of size $k$ can be shattered by $\mathscr{H}$, then $k$ is a break point for $\mathscr{H}$
- $m_{\mathscr{H}}(k)<2^{k}$
- VC dimension of $\mathscr{H}: k-1$ (the most points $\mathscr{H}$ can shatter)


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- VC dimension of $\mathscr{H}: k-1$ (the most points $\mathscr{H}$ can shatter)
- For 2-D perceptron: $k=4$, VC dimension $=3$


Can't generate


## Break point - examples

- Positive rays: $m_{\mathscr{H}}(N)=N+1$
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- Break point $k=3, d_{V C}=2$


## Break point - examples

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- Positive intervals: $m_{\mathscr{H}}(N)=\frac{1}{2} N^{2}+\frac{1}{2} N+1$
- Break point $k=3, d_{V C}=2$
- Convex set: $m_{\mathscr{H}}(N)=2^{N}$
- Break point $k=\infty, d_{V C}=\infty$
- Connection to \# of parameters


## We will show

- No break point $\Rightarrow m_{\mathscr{H}}(N)=2^{N}$
- Any break point $\Rightarrow m_{\mathscr{H}}(N)$ is polynomial in $N$


## Puzzle

- Break point is $k=2$



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$$
\begin{array}{lll}
x_{1} & x_{2} & x_{3} \\
\hline O & O & O \\
O & O & 0 \\
O & 0 & O \\
O & O & 0
\end{array}
$$

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- Key quantity:
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- Key quantity:
- $B(N, k)$ : Maximum number of dichotomies on $N$ points, with break $k$
- If the hypothesis space has break point $k$, then
- $m_{\mathscr{H}}(N) \leq B(N, k)$


## Recursive bound on $B(N, k)$

- For any "valid" set of dichotomies, reorganize rows by
- $S_{1}$ : pattern of $x_{1}, \ldots, x_{N-1}$ only appears once
- $S_{2}^{+}, S_{2}^{-}$: pattern of $x_{1}, \ldots, x_{N-1}$ only appears twice



## Recursive bound on $B(N, k)$

- Focus on $x_{1}, \ldots, x_{N-1}$ columns:
- $\alpha+\beta \leq B(N-1, k)$



## Recursive bound on $B(N, k)$

- Now focus on the $S_{2}=S_{2}^{+} \cup S_{2}^{-}$:
- $\beta \leq B(N-1, k-1)$



## Recursive bound on $B(N, k)$

$$
\begin{aligned}
B(N, k) & =\alpha+\beta+\beta \\
& \leq B(N-1, k)+B(N-1, k-1)
\end{aligned}
$$

- What's the upper bound for $B(N, k)$ ?


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$$

|  |  | k |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | 1 | 2 | 3 | 4 | 5 | $\ldots \ldots$ |  |
|  | N | 1 | 2 | 2 | 2 | 2 | $\ldots \ldots$ |
|  | 2 | 1 | 3 |  |  |  |  |
|  | 3 | 1 |  |  |  |  |  |
|  | 4 | 1 |  |  |  |  |  |
|  | 5 | 1 |  |  |  |  |  |
|  |  |  |  |  |  |  |  |
|  |  |  |  |  |  |  |  |
|  |  |  |  |  |  |  |  |

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## Analytic solution for $B(N, k)$ bound

- $B(N, k)$ is upper bounded by $C(N, k)$
- $C(N, 1)=1, N=1,2, \ldots$
- $C(1, k)=2, k=2,3, \ldots$
- $C(N, k)=C(N-1, k)+C(N-1, k-1)$
. Theorem: $C(N, k)=\sum_{i=0}^{k=1}\binom{N}{i}$


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- Boundary conditions: (easy to check)


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. Sauer's Theorem: $C(N, k)=\sum_{i=0}^{k-1}\binom{N}{i}$
- Boundary conditions: (easy to check)
- Induction:

$$
\text { - } \underbrace{\sum_{i=0}^{k-1}\binom{N}{i}}_{\text {select }<k \text { from } N \text { items }}=\underbrace{\sum_{i=0}^{k-1}\binom{N-1}{i}}_{N \text {-th item not chosen }}+\underbrace{\sum_{i=0}^{k-2}\binom{N-1}{i}}_{N \text {-th item chosen }}
$$

## It is polynomial!

- For a given $\mathscr{H}$, the break point $k$ is fixed:

$$
m_{\mathscr{H}}(N) \leq \quad \sum_{i=0}^{k-1}\binom{N}{i}
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Polynomial with degree $k-1$

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Polynomial with degree $k-1$
- $\mathscr{H}$ is positive rays: (break point $k=2$ )
- $m_{\mathscr{H}}(N)=N+1$


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- $m_{\mathscr{H}}(N)=$ ?


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- $\mathscr{H}$ is 2D perceptrons: (break point $k=4$ )
- $m_{\mathscr{H}}(N) \leq \frac{1}{6} N^{3}+\frac{5}{6} N+1$


## Replace M by $m_{\mathscr{H}}(N)$

- Original bound:
- $\mathbb{P}\left[\exists h \in \mathscr{H}\right.$ s.t. $\left.\left|E_{\mathrm{tr}}(h)-E(h)\right|>\epsilon\right] \leq 2 M e^{-2 \epsilon^{2} N}$
- Replace M by $m_{\mathscr{H}}(N)$

$$
\underbrace{\mathbb{P}\left[\exists h \in \mathscr{H} \text { s.t. }\left|E_{\mathrm{tr}}(h)-E(h)\right|>\epsilon\right]}_{B A D} \leq 2 \cdot 2 m_{\mathscr{H}}(2 N) \cdot e^{-\frac{1}{8} \epsilon^{2} N}
$$

- Vapnik-Chervonenkis (VC) bound


## VC dimension

## Definition

- The VC dimension of a hypothesis set $\mathscr{H}$, denoted by $d_{\mathrm{VC}}(\mathscr{H})$, is the largest value of $N$ for which $m_{\mathscr{H}}(N)=2^{N}$
- "The most points $\mathscr{H}$ can shatter"


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- "The most points $\mathscr{H}$ can shatter"
- $N \leq d_{\mathrm{VC}}(\mathscr{H}) \Rightarrow \mathscr{H}$ can shatter $N$ points
- $k>d_{\mathrm{VC}}(\mathscr{H}) \Rightarrow \mathscr{H}$ cannot be shattered
- The smallest break point is 1 above VC-dimension


## VC dimension

## The growth function

- In terms of a break point $k$ :
. $m_{\mathscr{H}}(N) \leq \sum_{i=0}^{k-1}\binom{N}{i}$
- In terms of the VC dimension $d_{\mathrm{VC}}$ :
- $m_{\mathscr{H}}(N) \leq \sum_{i=0}^{d \vee C}\binom{N}{i}$


## VC dimension

## VC dimension of linear classifier

- For $d=2, d_{\mathrm{VC}}=3$


## VC dimension <br> VC dimension of linear classifier

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- What if $d>2$ ?



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- In general,
- $d_{\mathrm{VC}}=d+1$



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- For $d=2, d_{\mathrm{VC}}=3$
- What if $d>2$ ?
- In general,
- $d_{\mathrm{VC}}=d+1$
- We will prove $d_{\mathrm{VC}} \geq d+1$ and $d_{\mathrm{VC}} \leq d+1$

